

# CS450

## Structure of Higher Level Languages

Lecture 17:  $\lambda_D$

Tiago Cogumbreiro

Press arrow keys   to change slides.

Shared "mutable" state  
with immutable data-structures

# Why immutability?

## Benefits

- A necessity if we use a language without mutation (such as Haskell)
- Parallelism: A great way to implement fast and safe data-structures in concurrent code (look up copy-on-write)
- Development: Controlled mutation improves code maintainability
- Memory management: counters the problem of circular references (notably, useful in C++ and Rust, see example)

Encoding shared mutable state with immutable data-structures is a great skill to have.

# Heap

We want to design a data-structure that represents a *heap* (a shared memory buffer) that allows us to: **allocate** a new memory cell, **load** the contents of a memory cell, and **update** the contents of a memory cell.

## Constructors

- `empty-heap` returns an empty heap
- `(heap-alloc h v)` creates a new memory cell in heap `h` whose contents are value `v`
- `(heap-put h r v)` updates the contents of memory handle `r` with value `v` in heap `h`

## Selectors

- `(heap-get h r)` returns the contents of memory handle `r` in heap `h`

# Heap usage

```
(define h empty-heap) ; h is an empty heap  
(define r (heap-alloc h "foo")) ; stores "foo" in a new memory cell
```

## What should the return value of `heap-alloc`?

- Should `heap-alloc` return a copy of `h` extended with "foo"? How do we access the memory cell pointing to "foo"?
- Should `heap-alloc` return a handle to the new memory cell? How can we access the new heap?

# Heap usage

```
(define h empty-heap) ; h is an empty heap  
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What should the return value of `heap-alloc`?

- Should `heap-alloc` return a copy of `h` extended with "foo"? How do we access the memory cell pointing to "foo"?
- Should `heap-alloc` return a handle to the new memory cell? How can we access the new heap?

Function `heap-alloc` must return a **pair** `eff` that contains the new heap and the memory handle.

```
(struct eff (state result) #:transparent)
```

# Heap usage example

## Spec

```
(define h1 empty-heap) ; h is an empty heap
(define r (heap-alloc h1 "foo")) ; stores "foo" in a new memory cell
(define h2 (eff-state r))
(define x (eff-result r)) ;
(check-equal? "foo" (heap-get h2 x)) ; checks that "foo" is in x
(define h3 (heap-put h2 x "bar")) ; stores "bar" in x
(check-equal? "bar" (heap-get h3 x)) ; checks that "bar" is in x
```

# Handles must be unique

We want to ensure that the handles we create are **unique**, otherwise allocation could overwrite existing data, which is undesirable.

Spec

```
(define h1 empty-heap)           ; h is an empty heap
(define r1 (heap-alloc h1 "foo")) ; stores "foo" in a new memory cell
(define h2 (eff-state r1))
(define x (eff-result r1))
(define r2 (heap-alloc h2 "bar")) ; stores "foo" in a new memory cell
(define h3 (eff-state r2))
(define y (eff-result r2))
(check-not-equal? x y) ; Ensures that x != y
(check-equal? "foo" (heap-get h3 x))
(check-equal? "bar" (heap-get h3 y))
```



How can we implement  
a memory handle?

# A simple heap implementation

- Let a handle be an integer
- Recall that the heap only grows (no deletions)
- A handle matches the number of elements already present in the heap
- When the heap is empty, the first handle is 0, the second handle is 1, and so on.

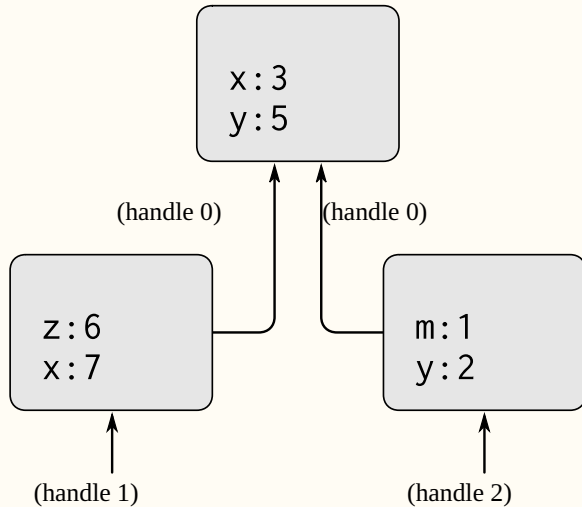
# Heap implementation

- We use a hash-table to represent the heap because it has a faster random-access than a linked-list (where lookup is linear on the size of the list).
- We wrap the hash-table in a struct, and the handle (which is a number) in a struct, for better error messages. And because it helps maintaining the code.

```
(struct heap (data) #:transparent)
(define empty-heap (heap (hash)))
(struct handle (id) #:transparent)
(struct eff (state result) #:transparent)
(define (heap-alloc h v)
  (define data (heap-data h))
  (define new-id (handle (hash-count data)))
  (define new-heap (heap (hash-set data new-id v)))
  (eff new-heap new-id))
(define (heap-get h k)
  (hash-ref (heap-data h) k))
(define (heap-put h k v)
  (define data (heap-data h))
  (cond
    [(hash-has-key? data k) (heap (hash-set data k v))]
    [else (error "Unknown handle!")]))
```

# Visualizing the environment

# Environment visualization

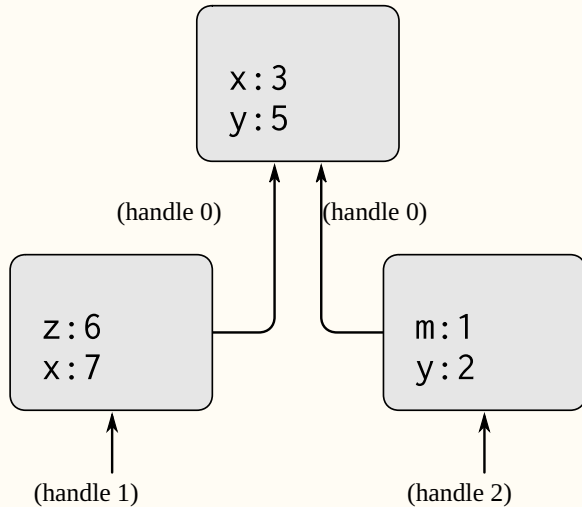


**Figure 3.1:** A simple environment structure.

Source: SICP book Section 3.2

```
; E0 = (handle 0)
E0: [
  (x . 3)
  (y . 5)
]
; E1 = (handle 1)
E1: [ E0
  (z . 6)
  (x . 7) ; shadows E0.x
  ; (y . 5)
]
; E2 = (handle 2)
E2: [ E0
  (m . 1)
  (y . 2) ; shadows E0.y
  ; (x . 3)
]
```

# Environment visualization



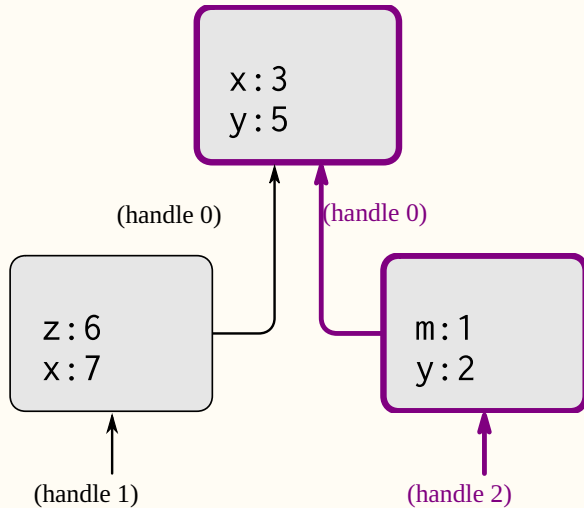
## The heap at runtime

- arrows are **references**, or heap handles:
- boxes are **frames**: labelled by their handles
- each frame has local variable bindings (eg, `m:1`, and `y:2`)

**Figure 3.1:** A simple environment structure.

Source: SICP book Section 3.2

# Environment visualization



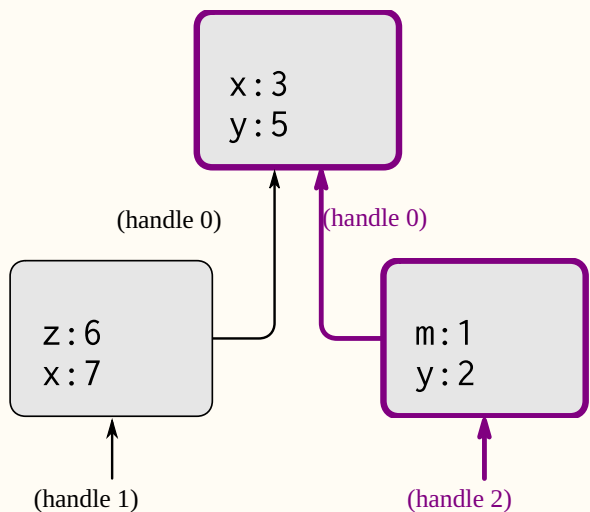
**Figure 3.1:** A simple environment structure.

Source: SICP book Section 3.2

## The heap at runtime

- arrows are **references**, or heap handles:
- boxes are **frames**: labelled by their handles
- each frame has local variable bindings (eg, `m:1`, and `y:2`)
- an **environment** represents a **sequence of frames**, connected via references. For instance, the environment that consists of frame 3 linked to frame 1.
- variable lookup follows the reference order. For instance, lookup a variable in frame 3 and then in frame 1.

# Quiz



List all variable bindings  
in environment `(handle 1)`

**Figure 3.1:** A simple environment structure.

Source: SICP book Section 3.2



# Implementing mutable environments

# Implementing mutable environments

## Heap

- A heap contains **frames**

## Frame

- a reference to its parent frame (except for the root frame which does not refer any other frame)
- a map of local bindings

Example of a frame: `[ E0 (y . 1) ]`

Example of a root frame: `[ (a . 20) (b . (closure E0 (lambda (y) a))) ]`

```
E0: [
  (a . 20)
  (b . (closure E0 (lambda (y) a)))
]
E1: [ E0
  (y . 1)
]
```

# Let us implement frames...

(demo time)

# Usage examples

```
; (closure E0 (lambda (y) a)
(define c (d:closure (handle 0) (d:lambda (list (d:variable 'y)) (d:variable 'a))))
;E0: [
; (a . 20)
; (b . (closure E0 (lambda (y) a)))
;]
(define f1
  (frame-put
    (frame-put root-frame (d:variable 'a) (d:number 10))
    (d:variable 'b) c))
(check-equal? f1 (frame #f (hash (d:variable 'a) (d:number 10) (d:variable 'b) c)))
; Lookup a
(check-equal? (d:number 10) (frame-get f1 (d:variable 'a)))
; Lookup b
(check-equal? c (frame-get f1 (d:variable 'b)))
; Lookup c that does not exist
(check-equal? #f (frame-get f1 (d:variable 'c)))
```

# More usage examples

```
; E1: [ E0
; (y . 1)
; ]
(define f2 (frame-push (handle 0) (d:variable 'y) (d:number 1)))
(check-equal? f2 (frame (handle 0) (hash (d:variable 'y) (d:number 1))))
(check-equal? (d:number 1) (frame-get f2 (d:variable 'y)))
(check-equal? #f (frame-get f2 (d:variable 'a)))
;; We can use frame-parse to build frames
(check-equal? (parse-frame '[ (a . 10) (b . (closure E0 (lambda (y) a))])]) f1)
(check-equal? (parse-frame '[ E0 (y . 1) ]) f2))
```

# Frames

```
(struct frame (parent locals))
```

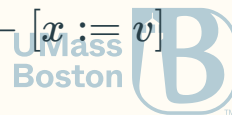
- `parent` is either `#f` or is a reference to the parent frame
- `locals` is a hash-table with the local variables of this frame

## Constructors

```
(struct frame (parent locals) #:transparent)
(define root-frame (frame #f (hash)))
(define (frame-push parent var val)
  (frame parent (hash var val)))
(define (frame-put frm var val)
  (frame (frame-parent frm)
         (hash-set (frame-locals frm) var val)))
(define (frame-get frm var)
  (hash-ref (frame-locals frm) var #f))
```

## Description

- `root-frame` creates an orphan empty frame (hence `#f`). This function is needed to represent the top-level environment.
- `frame-push` takes a reference that points to the parent frame, and initializes a hash-table with one entry (`var`, `val`). This function is needed for  $E \leftarrow E' + [x := v]$
- `frame-put` updates the current frame with a new binding. This function is needed for  $E \leftarrow [x := v]$



# Summary

Today we implement a mutable environment.

## Constructors

- **Empty:** The empty, root environment.
- **Put:**  $E \leftarrow [x := v]$  updates an existing environment  $E$  upon defining a variable. Returns the same frame, and updates the heap.
- **Push:**  $E_2 \leftarrow E_1 + [x := v]$  creates a new environment  $E_2$  by extending environment  $E_1$  with one binding  $x = v$ . Returns the new environment.

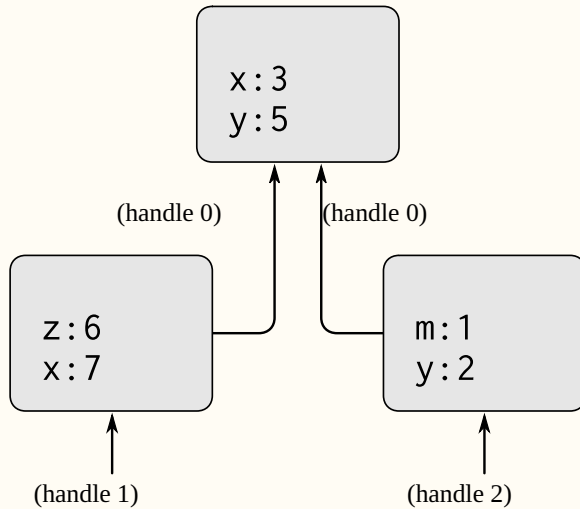
## Selectors

- **Variable Lookup:**  $E(x)$  Looks up variable  $x$  in the bindings of the current frame, otherwise recursively looks up the parent frame.



# Environment example

## Environment visualization



## Environment operations

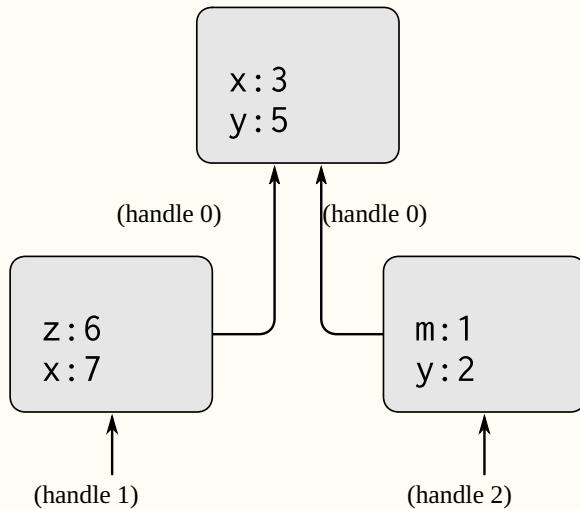
**Figure 3.1:** A simple environment structure.

Source: SICP book Section 3.2



# Environment example

## Environment visualization



**Figure 3.1:** A simple environment structure.

Source: SICP book Section 3.2

## Environment operations

```
E0 <- [x := 3]
E0 <- [y := 5]
E1 <- E0 + [z := 6]
E1 <- [x := 7]
E2 <- E0 + [m := 1]
E2 <- [y := 2]
```

# Constructors: Root

## The root environment

```
(define root-alloc (heap-alloc empty-heap root-frame))  
(define root-environ (eff-result root-alloc))  
(define root-mem (eff-state root-alloc))
```

# Constructors: Put

$$E \leftarrow [x := v]$$

```
(define (environ-put mem env var val)
  (define new-frm (frame-put (heap-get mem env) var val))
  (heap-put mem env new-frm))
```

Example

In Racket

```
E0 <- [x := 3]
E0 <- [y := 5]
```

# Constructors: Put

$$E \leftarrow [x := v]$$

```
(define (environ-put mem env var val)
  (define new-frm (frame-put (heap-get mem env) var val))
  (heap-put mem env new-frm))
```

Example

```
E0 <- [x := 3]
E0 <- [y := 5]
```

In Racket

```
(define E0 root-environ)
(define m1
  (environ-put
    (environ-put root-heap E0 (d:variable 'x) (d:number 3))
    E0 (d:variable 'y) (d:number 5)))
```

# Constructors: Push

$$E_2 \leftarrow E_1 + [x := v]$$

```
(define (environ-push mem env var val)
  (define new-frame (frame env (hash var val)))
  (heap-alloc mem new-frame))
```

Example

In Racket

```
E1 <- E0 + [z := 6]
E1 <- [x := 7]
```

# Constructors: Push

$$E_2 \leftarrow E_1 + [x := v]$$

```
(define (environ-push mem env var val)
  (define new-frame (frame env (hash var val)))
  (heap-alloc mem new-frame))
```

Example

```
E1 <- E0 + [z := 6]
E1 <- [x := 7]
```

In Racket

```
(define e1-m2 (environ-push m1 E0 (d:variable 'z) (d:number 6)))
(define E1 (eff-result e1-m2))
(define m2 (eff-state e1-m2))
(define m3 (environ-put m2 E1 (d:variable 'x) (d:number 7)))
```

# Continuing the example

Example

In Racket

```
E0 <- [x := 3]
E0 <- [y := 5]
E1 <- E0 + [z := 6]
E1 <- [x := 7]
E2 <- E0 + [m := 1]
E2 <- [y := 2]
```

# Continuing the example

Example

```
E0 <- [x := 3]
E0 <- [y := 5]
E1 <- E0 + [z := 6]
E1 <- [x := 7]
E2 <- E0 + [m := 1]
E2 <- [y := 2]
```

In Racket

```
(define E0 root-environ)
(define m1
  (environ-put
    (environ-put root-heap E0 (d:variable 'x) (d:number 3))
    E0 (d:variable 'y) (d:number 5)))
(define e1-m2 (environ-push m1 E0 (d:variable 'z) (d:number 6)))
(define E1 (eff-result e1-m2))
(define m2 (eff-state e1-m2))
(define m3 (environ-put m2 E1 (d:variable 'x) (d:number 7)))
(define e2-m4 (environ-push m3 E0 (d:variable 'm) (d:number 1)))
(define E2 (eff-result e2-m4))
(define m4 (eff-state e2-m4))
(define m5 (environ-put m4 E2 (d:variable 'y) (d:number 2)))
```



# Selector: Variable lookup

$E(x)$

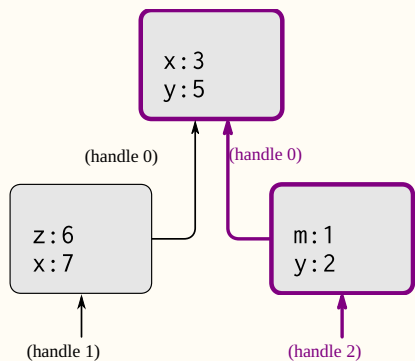
```
(define (environ-get mem env var)
  (define frm (heap-get mem env))    ;; Load the current frame
  (define parent (frame-parent frm)) ;; Load the parent
  (define result (frame-get frm var)) ;; Lookup locally
  (cond
    [result result] ;; Result is defined, then return it
    [parent (environ-get mem parent var)] ; If parent exists, recurse
    [else (error (format "Variable ~a is not defined" var))]))
```

Example

```
(check-equal? (environ-get m5 E2 (d:variable 'y)) (d:number 2))
(check-equal? (environ-get m5 E2 (d:variable 'm)) (d:number 1))
(check-equal? (environ-get m5 E2 (d:variable 'x)) (d:number 3))
```

# A language of environments

## Environment visualization



**Figure 3.1:** A simple environment structure.

Source: SICP book Section 3.2

```
(define parsed-m5
  (parse-mem
    '([E0 . ([x . 3] [y . 5])]
      [E1 . (E0 [x . 7] [z . 6])]
      [E2 . (E0 [m . 1] [y . 2]))]))
```

*; Which is the same as creating the following data-structure*

```
(heap
  (hash
    (handle 0)
    (frame #f
      (hash (d:variable 'y) (d:number 5) (d:variable 'x) (d:number 3)))
    (handle 2)
    (frame (handle 0)
      (hash (d:variable 'y) (d:number 2) (d:variable 'm) (d:number 1)))
    (handle 1)
    (frame (handle 0)
      (hash (d:variable 'z) (d:number 6) (d:variable 'x) (d:number 7))))
```

```
(check-equal? parsed-m5 m5)
```

$$\frac{\blacktriangleright_{H_1} e \Downarrow_E v \quad \blacktriangleright_{H_2} E \leftarrow [x := v] \blacktriangleright_{H_3}}{\blacktriangleright_{H_1} (\text{define } x \ e) \Downarrow_E \text{void} \blacktriangleright_{H_3}}$$

$$\frac{\blacktriangleright_{H_1} t_1 \Downarrow_E v_1 \quad \blacktriangleright_{H_2} t_2 \Downarrow_E v_2 \blacktriangleright_{H_3}}{t_1; t_2 \Downarrow_E v_2}$$

$$\blacktriangleright_H v \Downarrow_E v \blacktriangleright_H$$

$$\blacktriangleright_H x \Downarrow_E E(x) \blacktriangleright_H$$

$$\blacktriangleright_H \lambda x. t \Downarrow_E (E, \lambda x. t) \blacktriangleright_H$$

$$\frac{\blacktriangleright_{H_1} e_f \Downarrow_E (E_f, \lambda x. t_b) \quad \blacktriangleright_{H_2} e_a \Downarrow_E v_a \quad \blacktriangleright_{H_3} E_b \leftarrow E_f + [x := v_a] \quad \blacktriangleright_{H_4} t_b \Downarrow_{E_b} v_b \quad \blacktriangleright_{H_5}}{\blacktriangleright_{H_1} (e_f \ e_a) \Downarrow_E v_b \blacktriangleright_{H_5}}$$

# Notes

- Make sure `(d:eval-term)` handles expressions by calling `(d:eval-exp)`
- Make sure the case for `d:define?` returns the value `(d:void)` not `(void)`, not `d:void`, not `void`
- Make sure the case for `d:apply?` invokes `(d:eval-term)` when handling  $t_b$

# Exercise

```
;; e1  $\Downarrow$ E v1
```

```
;; E' <- E + [x := v1]
```

```
;; e2  $\Downarrow$ E' v2
```

# Exercise

```
;; e1 ↓E v1
(define v1+mem1 (d:eval-exp mem env e1))
(define mem1 (eff-state v1+mem1))
(define v1 (eff-result v1+mem1))
;; E' ← E + [x := v1]
(define env2+mem2 (environ-push mem1 env y v1))
(define env2 (eff-result env2+mem2))
(define mem2 (eff-state env2+mem2))
;; e2 ↓E' v2
(define v2+mem3 (d:eval-exp mem2 env2 e2))
(define mem3 (eff-state v2+mem3))
(define v2 (eff-result v2+mem3))
```