

CS420

Introduction to the Theory of Computation

Lecture 12: Turing Machines

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Today we will learn...

- Introduce Turing Machines
- Design Turing Machines
- Define Turing machines
- Configuration
- Configuration history

Section 3.1

You might enjoy this...

- A Mind for Numbers, Barbara Oakley. ([audio book is free @ UMB Library](#)).

1. Recap

- Deterministic Finite Automaton that recognize Regular Languages
- Pushdown Automaton that recognize Context-Free Languages

2. Turing Machines

- Introduced to research into the **foundations of mathematics**
- characterizes **computation**
- can represent any computable machine unbounded by time and space

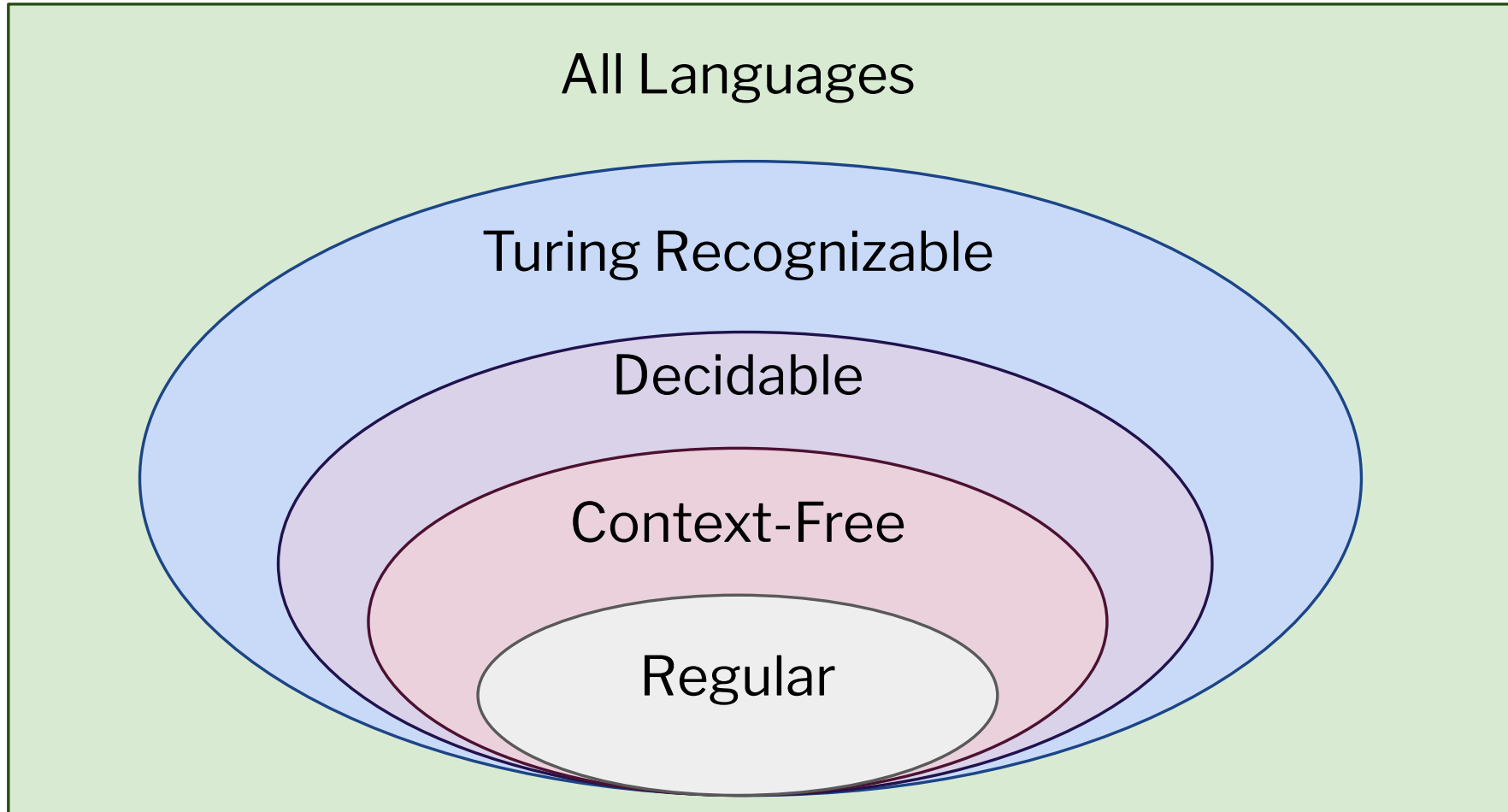
In general, describes problems of the form:

Decide for any given x whether or not x has property P

Next lecture

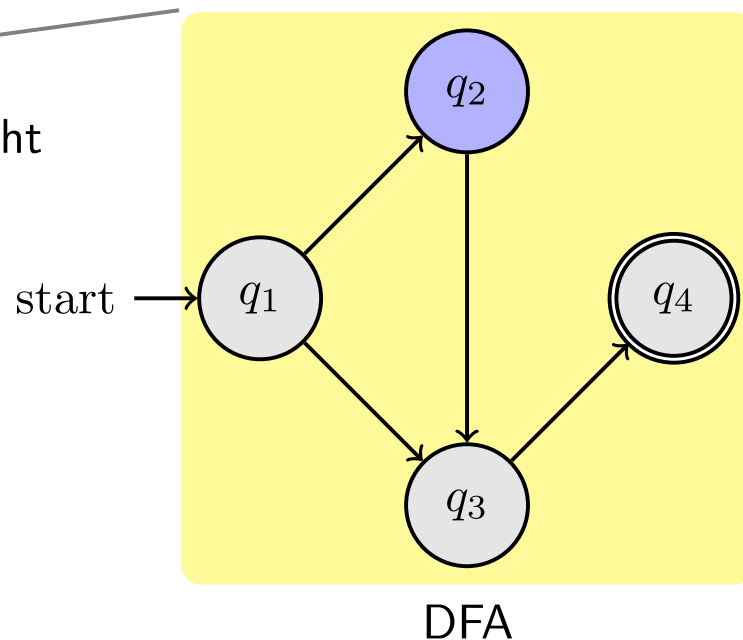
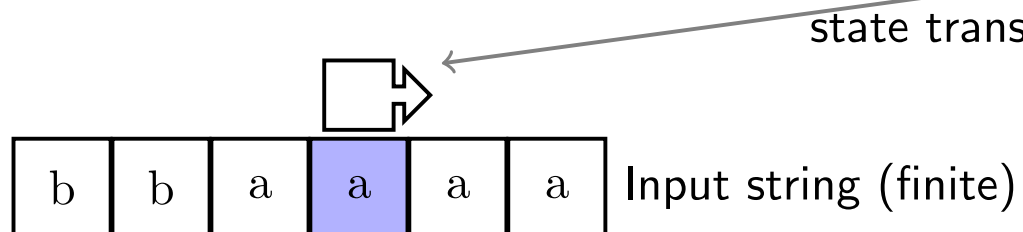
- Historical background on Turing machines

The big picture



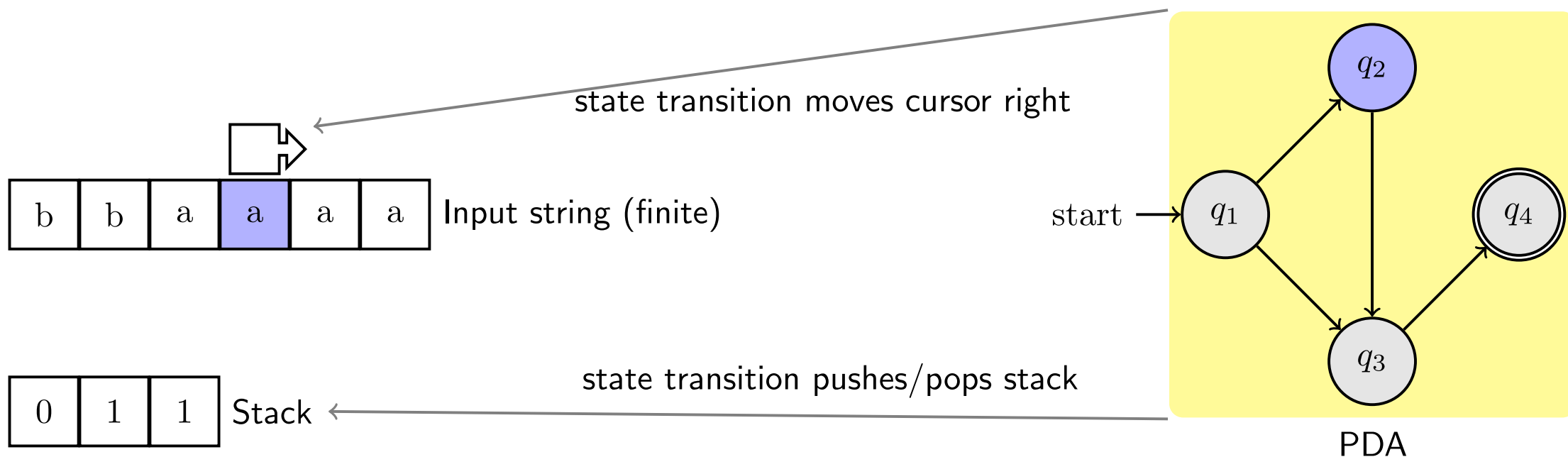
Recall DFA operation

- Automaton processes a finite input string (acceptance)
- Transition moves the cursor forward
- Final state accepts the string if the cursor is at the end



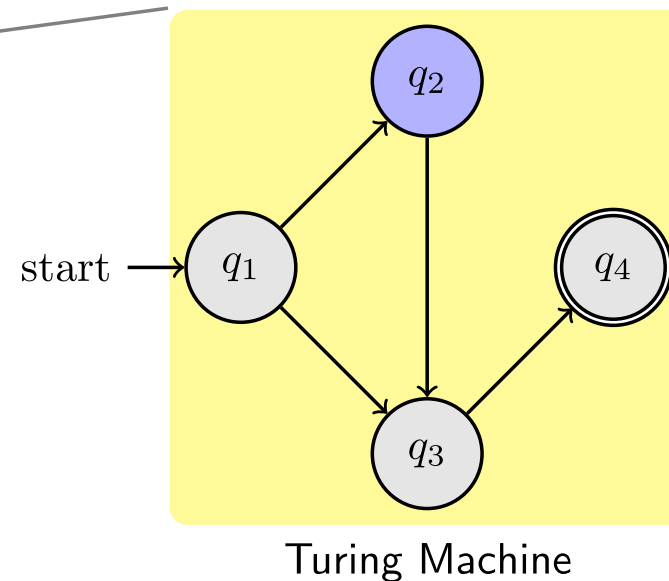
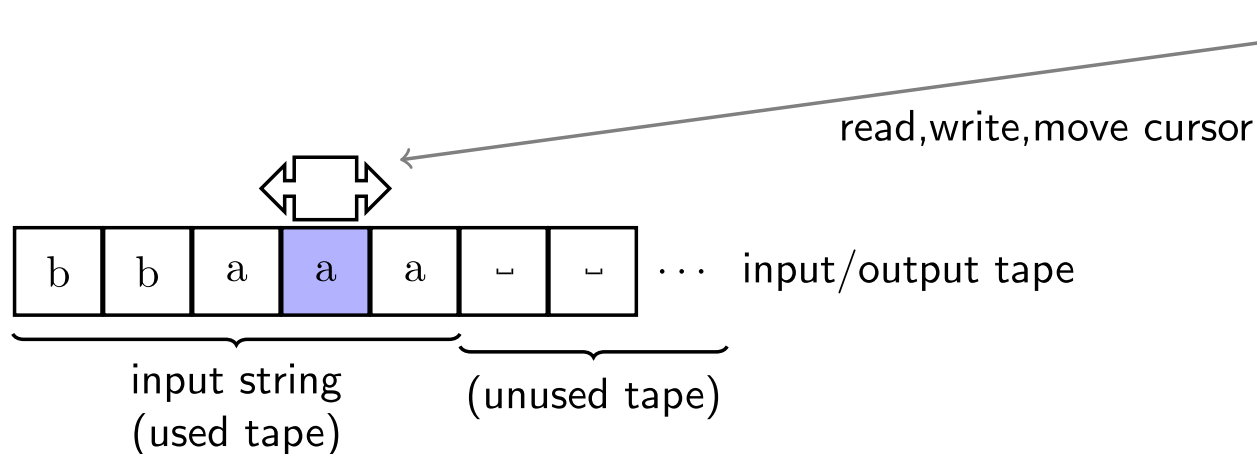
Recall PDA operation

- Automaton processes a finite input string (acceptance) and a stack
- Transition may move the cursor forward and may push/pop the stack
- Final state accepts the string if the cursor is at the end



Turing Machine operation

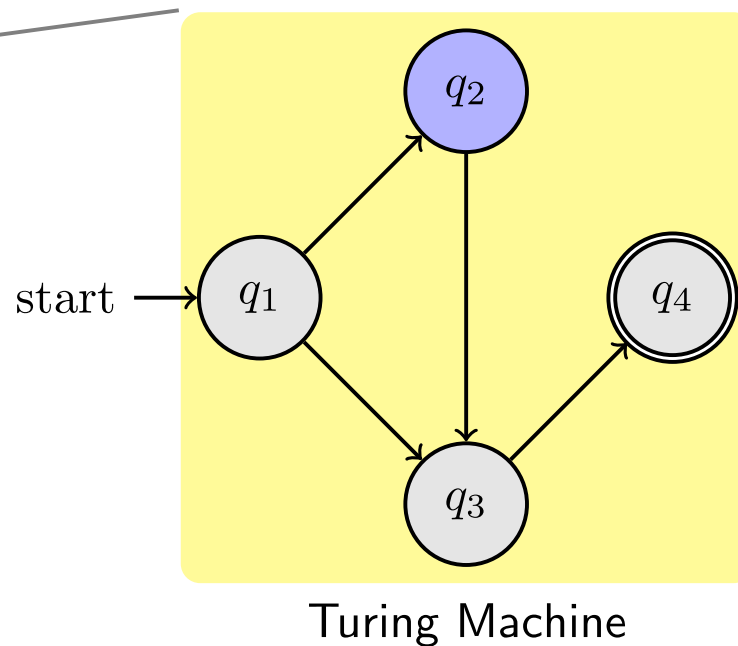
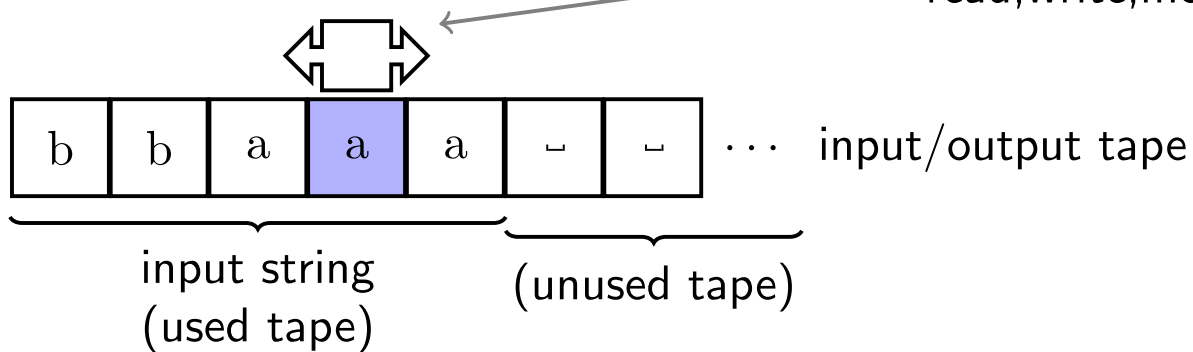
- Automaton processes an **infinite tape**
- Transition may move the cursor forward **or backward**
- Elements of the tape may be written or read (tape combines the input string and the stack)
- Tapes may contain a special character called blank, notation \sqcup (akin to NULL)



Turing Machine operation

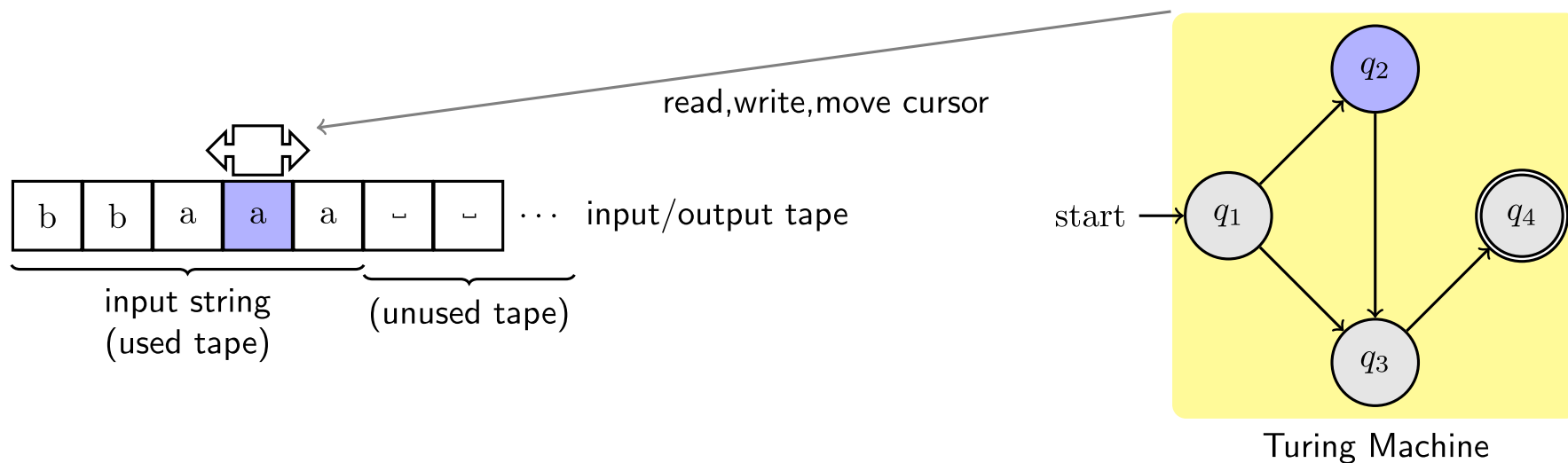
- The **tape head** (or cursor) points to a position in the tape (akin the instruction pointer in a processor)
- Transition: read \rightarrow write, move direction

$$q \xrightarrow{a \rightarrow b, R} q'$$



Turing Machine control

- The automaton (the turing machine) is known as the **control** or the **program**
- The automaton is deterministic (nondeterminism has same expressiveness!)
- A single initial state
- A single accept state
- A reject state



Turing Machines acceptance

Given a tape (with an ϵ) and a Turing machine, there are three kinds of answers:

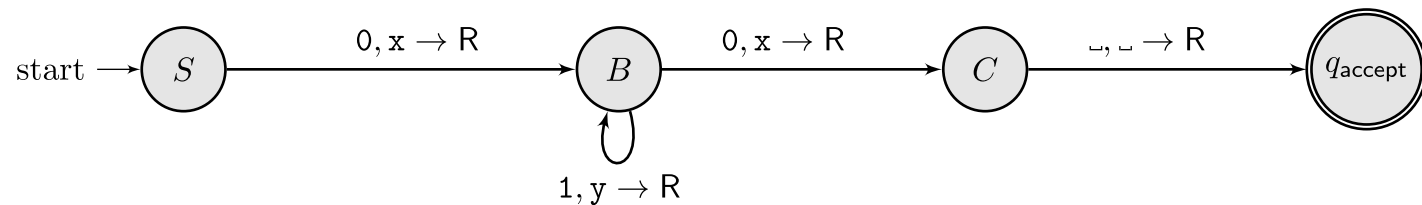
- **Accept**
Whenever the machine reaches the accept state, the automaton halts and the input string is accepted.
- **Reject**
Whenever the machine reaches the reject state, the automaton halts and the input string is rejected.
- **Loop forever**
The machine keeps doing transitions in a loop, never accepting nor rejecting the input string.

While a PDA and a DFA can either accept or reject a string, a Turing machines can also loop forever!

Examples

Example 1

$$L = 01^*0$$



- Deterministic (only one outgoing edge **per input**)
- **Convention:** missing transitions go to reject state (hidden).

Example

State	Tape
<i>S</i>	<u>0</u> 1110
<i>B</i>	x <u>1</u> 110
<i>B</i>	xy <u>1</u> 10
<i>B</i>	xyy <u>1</u> 0
<i>B</i>	xyyy <u>0</u>
<i>C</i>	xyyyx <u>_</u>
<i>q_{accept}</i>	xyyyx <u>_</u>

Simulate

Example 2

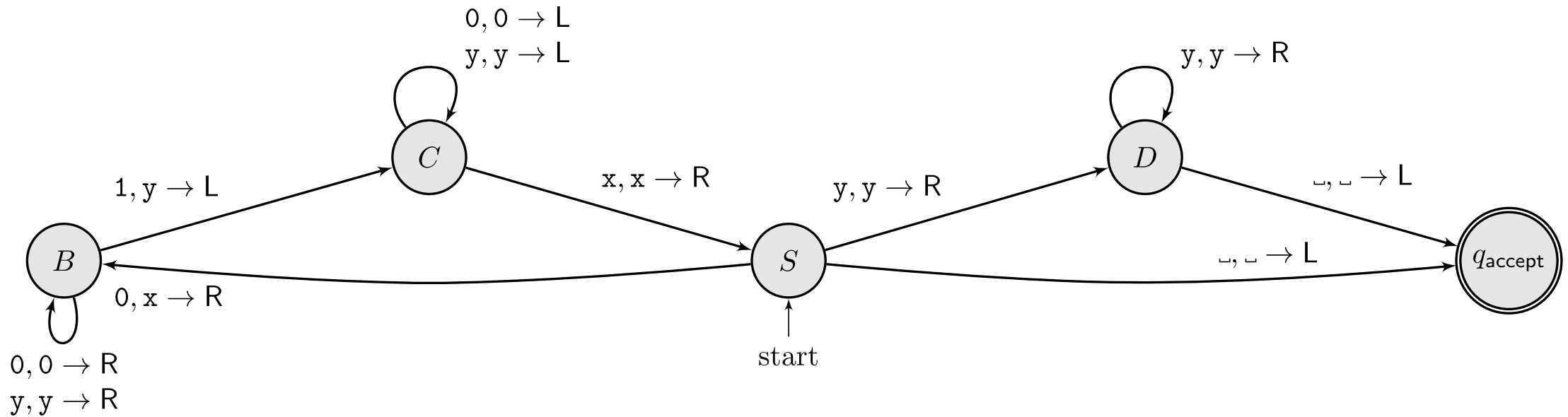
$$L_1 = \{0^n 1^n \mid n \geq 0\}$$

Mark 0 seek and mark 1 and cycle back.

- **Start (S):** if \emptyset {write X; move right; goto B}; if Y {skip right; goto D}
- **Seek 0 (B):** while 1 or X {skip right};if 1 {write Y; move right; goto C}
- **Seek 1 (C):** while \emptyset or Y {skip left};if X {skip; move right; goto S}
- **Check valid (D):** while Y {skip right};if \sqcup {skip;move right; goto accept}

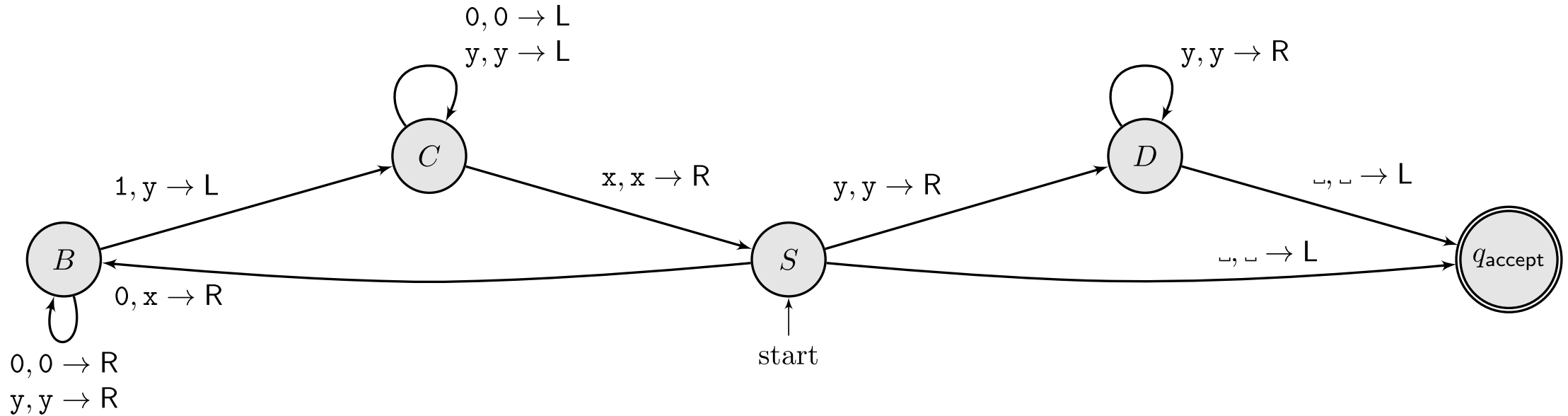
Tape	State	Rule
<u>0</u> 011	S	read \emptyset ; write X; move right; goto B
X0 <u>1</u> 1	B	skip right while 1 or x; if 1 {write Y; move right; goto C}
X0Y <u>1</u>	C	skip left while \emptyset or y; if x {skip; move right; goto S}
X <u>0</u> Y1	S	read \emptyset ; write x; move right; goto B
XXY <u>1</u>	B	skip right while 1 or x; if 1 {write Y; move right; goto C}
XX <u>Y</u> Y	C	skip left while \emptyset or y; if x {skip; move right; goto S}
XX <u>Y</u> Y	S	read y; skip right; goto D
XXYY <u>□</u>	D	read \sqcup , goto accept

Example 2



State	Tape
S	0011
B	X011
B	X011
C	X0Y1

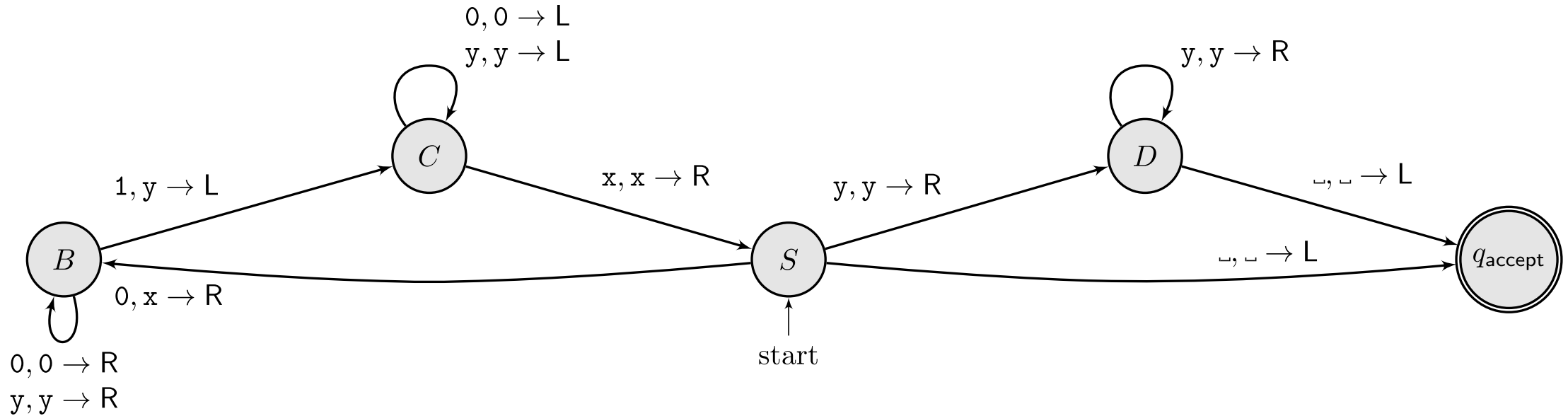
Example 2



State	Tape
S	0011
B	X011
B	X011
C	X0Y1

State	Tape
C	X0Y1
S	X0Y1
B	XXY1
B	XXY1

Example 2

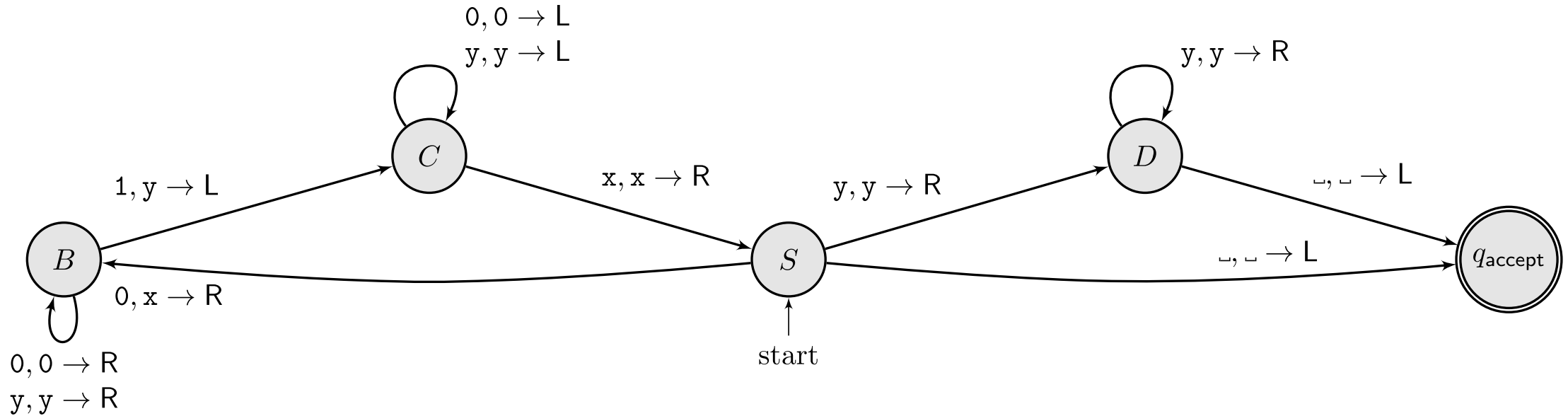


State	Tape
S	0011
B	X011
B	X011
C	X0Y1

State	Tape
C	X0Y1
S	X0Y1
B	XXY1
B	XXY1

State	Tape
C	XXYY
C	XXYY
S	XXYY
D	XXYY

Example 2



State	Tape
S	0011
B	X011
B	X011
C	X0Y1

State	Tape
C	X0Y1
S	X0Y1
B	XXY1
B	XXY1

State	Tape
C	XXYY
C	XXYY
S	XXYY
D	XXYY

State	Tape
D	XXYY \sqcup

Accept!

Simulate

Example 3

$$L_3 = \{a^n b^n c^n \mid n \geq 0\}$$

Example 3

$$L_3 = \{a^n b^n c^n \mid n \geq 0\}$$

- **START:** Skip marks **right** until we: i) read a; mark it; go to A; ii) read blank, accept.
- **A:** Skip **right** until read b; mark it; go to Bs
- **B:** Skip **right** until read c; mark it; go to Cs
- **C:** Skip **right** until read blank; move left; go to REWIND
- **REWIND:** Skip **left** until we reach blank, go to START

Simulate

Turing Machines

Definition 3.3

A Turing machine is a 7-tuple $(Q, \Sigma, \Gamma, \delta, q_0, q_{accept}, q_{reject})$

1. Q set of states
2. Σ input alphabet not containing the blank symbol \sqcup
3. Γ the tape alphabet, where $\sqcup \in \Gamma$ and $\Sigma \subseteq \Gamma$
4. $\delta : Q \times \Gamma \rightarrow Q \times \Gamma \times \{L, R\}$ transition function
5. $q_0 \in Q$ is the start state
6. q_{accept} is the accept state
7. q_{reject} is the reject state ($q_{reject} \neq q_{accept}$)

Configuration

A configuration is a snapshot of a computation. That is, it contains all information necessary to resume (or replay) a computation from any point in time.

A configuration consists of

- the tape
- the head of the tape
- the current state

Configuration

Textual notation

We write the table and place the current state **before** (left of) where the head of the tape points to:

In the following example, the head points to position no.5, the tape is 0130045, and the current state is q_3 :

Recall example 1

State	Tape	Configuration
S	<u>0</u> 1110	S 01110
B	x <u>1</u> 110	
B	xy <u>1</u> 10	
B	xyy <u>1</u> 0	
B	xyyy <u>0</u>	
B	xyyyx <u>_</u>	

Fill in the configuration...

Example 1 configuration

<i>State</i>	<i>Tape</i>	<i>Configuration</i>
<i>S</i>	<u>0</u> 1110	S 01110
<i>B</i>	x <u>1</u> 110	x B 1110
<i>B</i>	xy <u>1</u> 10	xy B 110
<i>B</i>	xyy <u>1</u> 0	xyy B 10
<i>B</i>	xyyy <u>0</u>	xyyy B 0
<i>B</i>	xyyyx <u>_</u>	xyyyx B

Configuration history

The configuration history (sequence of configurations), describes all configurations from the initial state until a current state.

Definition

We say that C_1 **yields** C_2

Example

Configuration history
S 01110
x B 1110
xy B 110
xyy B 10
xyyy B 0
xyyyx B

More examples

- $L_5 = \{w\#w \mid w \in \{a, b\}^*\}$
- $L_6 = \{w \mid w \text{ is a palindrome}\}$
- $L_7 = \{a^n b^{2n} \mid n \geq 0\}$